#### Lecture 10 - Oct 6

# <u>Graphs</u>

Forest vs. Tree vs. Spanning Tree Graph Traversal: Depth-First Search (DFS) DFS on a Tree vs. Pre-Order Traversal

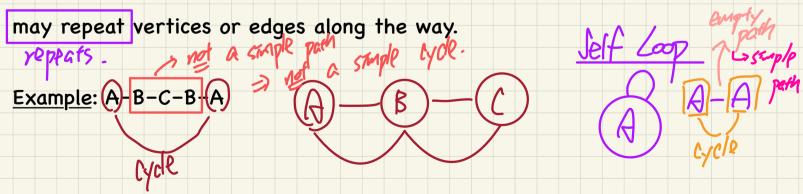
#### Simple cycle:

A closed path that starts and ends at the same vertex and does not repeat any vertex or edge except for the starting/ending vertex.

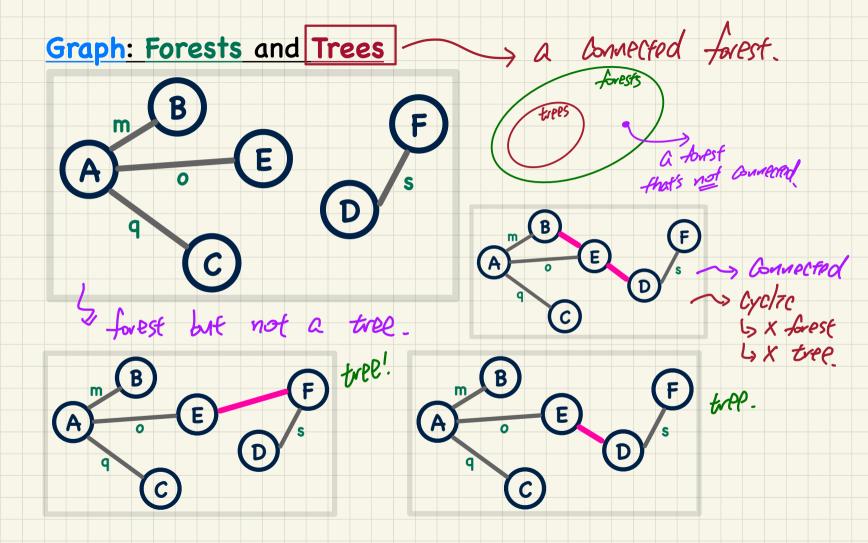
Example: A-B-

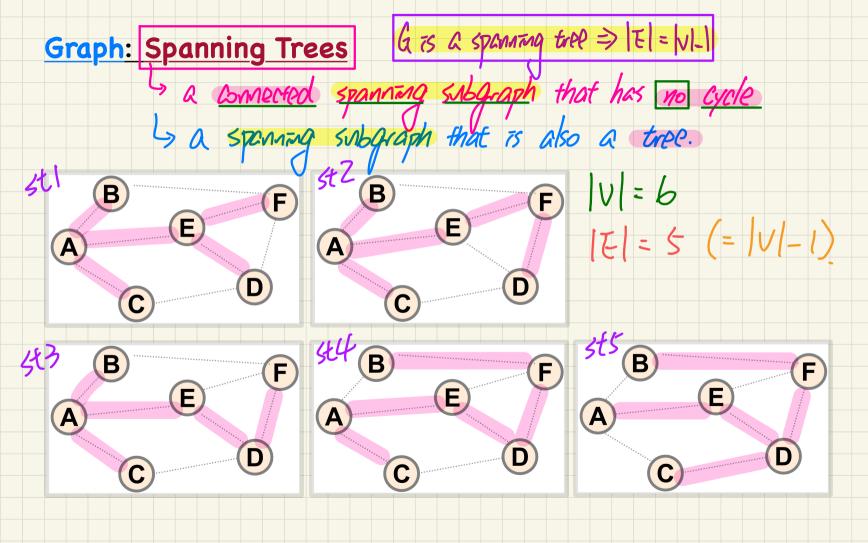
Non-simple cycle:

A closed path that starts and ends at the same vertex but



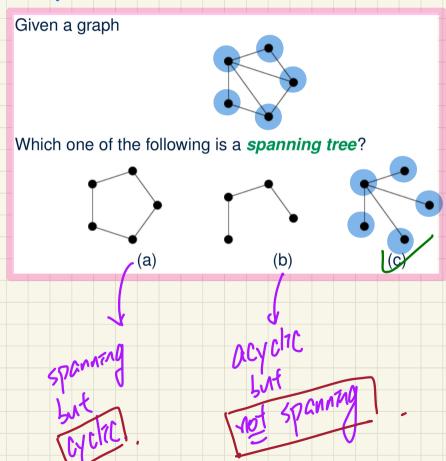
> undirected Graph: Forests and Trees - no cycle (acyclec) Any two vertices are americal via \* at most one path. What of >2 edges commercing two vertices. \* Special case: if u and v are competed by 0 = edge ~> the graph is not A forest may or may not be connected.

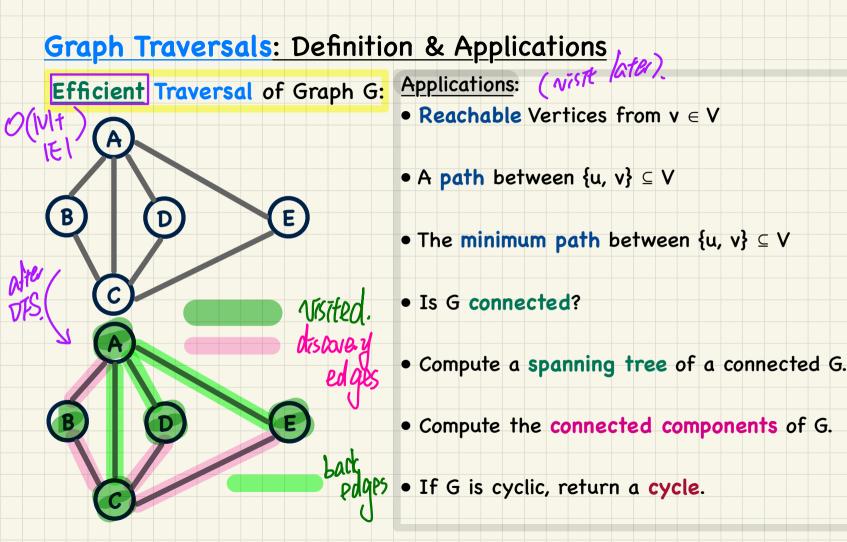




Summary of Terms subgraph spanning subgraph forest tree spanning tree Undwerfed acyclic? Connected

## **Graph:** Exercises





	Graph Traversal: Depth-First Search (DFS) display edges.
_	A <b>Depth-First Search</b> ( <b>DFS</b> ) of graph G = (V, E),
ď	<ul> <li>starting from some vertex v ∈ V, proceeds along a path from v.</li> <li>The path is constructed by following an incident edge.</li> </ul>
	The path is extended as far as possible until all incident edges lead to vertices that have already been visited.
	<ul> <li>Once the path originated from v cannot be extended further,</li> </ul>
	backtrack to the latest vertex whose incident edges lead to some unvisited vertices.
	Assumption: iterate through neighbours alphabetically.
	Q. When a graph is a tree,
	what kind of tree traversal does it correspond to?
	pre-order (parent first, children next).
	Q. What data structure should be used to say all these
	keep track of the visited nodes?  notification with the visited nodes?
	Stack. (LIFO).

A

### Depth-First Search (DFS): Marking Vertices & Edges

#### Before the **DFS** starts:

- All vertices are unvisited.
- All edges are unexplored/unmarked.

Over the course of a **DFS**, we **mark** vertices and edges:

- A vertex *v* is marked *visited* when it is **first** encountered.
- Then, we iterate through each of v's **incident edges**, say e:
  - If edge e is already marked, then skip it.
  - Otherwise, mark edge e as:
    - A *discovery* edge if it leads to an *unvisited* vertex

